Stochastic Calculus II

Solutions 8

1. a) Since W_t is a sum of stochastic integrals, it is a (continuous) martingale. Its quadratic variation is given by

$$\langle W \rangle_t = \sum_{i,k=1}^n \int_0^t \frac{B_s^{(i)} B_s^{(k)}}{\|\underline{\mathbf{B}}_s\|^2} \, d\langle B^{(i)}, B^{(k)} \rangle_s = \sum_{i=1}^n \int_0^t \frac{(B_s^{(i)})^2}{\|\underline{\mathbf{B}}_s\|^2} \, ds = \int_0^t 1 \, ds = t.$$

Therefore, by Lévy's theorem, W_t is a standard Brownian motion.

b) For $\underline{\mathbf{x}} \neq 0$, we have

$$f'_{x_i}(\underline{\mathbf{x}}) = rac{x_i}{\|\underline{\mathbf{x}}\|} \quad ext{and} \quad f''_{x_i,x_k}(\underline{\mathbf{x}}) = rac{\delta_{ik}}{\|\underline{\mathbf{x}}\|} - rac{x_i \, x_k}{\|\underline{\mathbf{x}}\|^3},$$

so $\Delta f(\underline{\mathbf{x}}) = \frac{n-1}{\|\underline{\mathbf{x}}\|}$ and

$$\|\underline{\mathbf{B}}_t\| = \sum_{i=1}^n \int_0^t \frac{B_s^{(i)}}{\|\underline{\mathbf{B}}_s\|} \, dB_s^{(i)} + \frac{1}{2} \int_0^t \frac{n-1}{\|\underline{\mathbf{B}}_s\|} \, ds.$$

By using the result in part a), we therefore obtain that $R_t = ||\underline{\mathbf{B}}_t||$ satisfies the equation

$$R_t = W_t + \int_0^t \frac{n-1}{2R_s} \, ds$$

2. a)
$$A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$
, $\Sigma = \begin{pmatrix} 0 \\ \sigma \end{pmatrix}$ and $\underline{z}_0 = \begin{pmatrix} x_0 \\ 0 \end{pmatrix}$.

b) By the class, we know that $\Phi_t = \exp(tA)$, where

$$\exp(tA) = \sum_{n=0}^{\infty} \frac{t^n A^n}{n!}$$

As $A^2 = -I$, we obtain that $A^{2k} = (-1)^k I$, $A^{2k+1} = (-1)^k A$ and

$$\exp(tA) = \sum_{k=0}^{\infty} (-1)^k \frac{t^{2k}}{(2k)!} I + \sum_{k=0}^{\infty} (-1)^k \frac{t^{2k+1}}{(2k+1)!} A = \cos(t) I + \sin(t) A = \begin{pmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{pmatrix}.$$

c) These formulas are easily proved using trigonometric relations such as $\cos(-t) = \cos(t)$ and $\cos(t+s) = \cos(t)\cos(s) - \sin(t)\sin(s)$.

d) By the class, we know that

$$\underline{Z}_t = \int_0^t \Phi_{t-s} \,\Sigma \, d\underline{B}_s + \Phi_t \, \underline{z}_0.$$

Therefore,

$$X_t = \sigma \int_0^t \sin(t-s) \, dB_s + \cos(t) \, x_0$$
 and $Y_t = \sigma \int_0^t \cos(t-s) \, dB_s - \sin(t) \, x_0.$

e) $\frac{dX_t}{dt} = \lim_{\varepsilon \to 0} \frac{1}{\varepsilon} (X_{t+\varepsilon} - X_t) = \lim_{\varepsilon \to 0} \frac{1}{\varepsilon} \int_t^{t+\varepsilon} \sin(t+\varepsilon-s) \, dB_s + Y_t = Y_t,$ as $\mathbb{E}((\frac{1}{\varepsilon} \int_t^{t+\varepsilon} \sin(t+\varepsilon-s) \, dB_s)^2) = \frac{1}{\varepsilon^2} \int_t^{t+\varepsilon} \sin(t+\varepsilon-s)^2 \, ds = \frac{1}{2\varepsilon^2} (\varepsilon - \sin(2\varepsilon)/2) = O(\varepsilon).$