

Lecture 11. Application of the Bethe free energy to coding. The connection between MAP and BP decoding.

We apply the formalism developed last time to coding. This leads us to a conjecture concerning the link between MAP & BP decoding. The ideas for the proof of this conjecture in the BEC are outlined.

1. Ensemble average of Bethe free energy and Replica symmetric or Trivial entropy.

Gallager ensemble  $(DPC(l, r))$ .  
BMS channel  $p(y|x)$

The associated graphical model has "Gibbs" or "MAP" distribution (see lecture no 4).

$$p(s_1, \dots, s_N | y_1, \dots, y_N) = \frac{1}{Z(h)} \prod_a \frac{1}{2} (1 + \frac{\prod_i s_i}{i \alpha}) \prod_c \frac{1}{2} (1 + \frac{\prod_i s_i}{i \alpha})$$

view these as  
pot nodes of  
degree 1.

$$h_i = \frac{1}{2} \ln \frac{p(z_i | s_i = +1)}{p(z_i | s_i = -1)}$$

(input word is "all zero codeword" :  $s_i = +1$  all  $i$ )

Recall (lecture 4) :

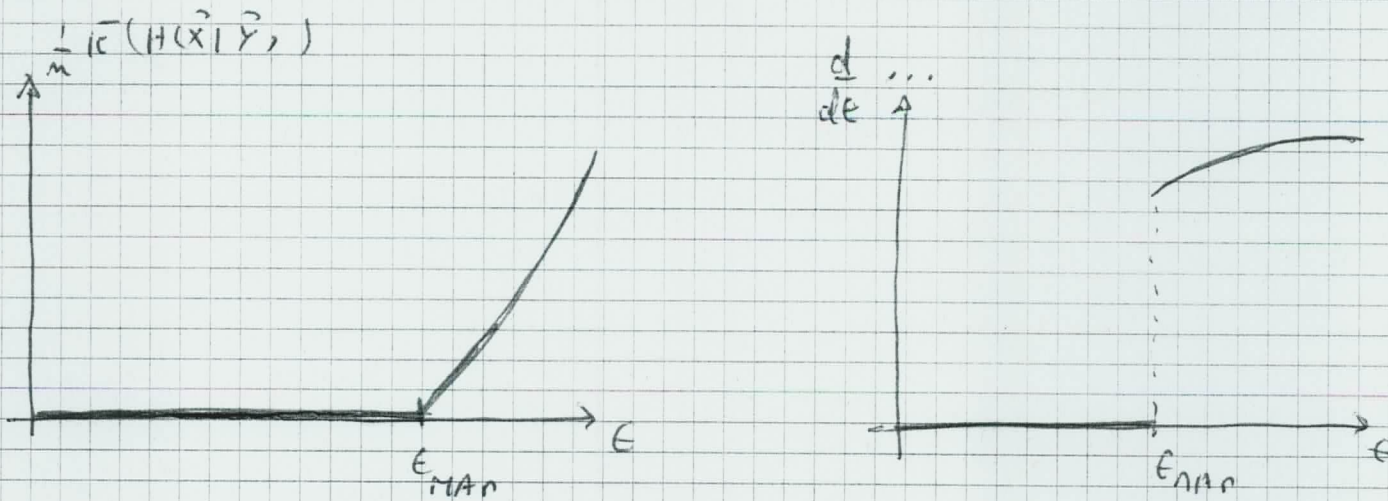
$$\frac{1}{m} \bar{E}_{\text{LDPC}} (H(\vec{x} | \vec{y})) = \frac{1}{m} \bar{E}_{\text{LDPC}} \int_{\mathcal{h}} \ln Z(\vec{h}) - \int d\mathbf{h} h c(\mathbf{h})$$

where  $c(\mathbf{h}) = \text{channel density (L-domain)}$ .

Performance curve (MAP - EXIT function)

$$\frac{d}{dE} \frac{1}{m} \bar{E}_{\text{LDPC}} (H(\vec{x} | \vec{y})) \quad \begin{matrix} \text{slope} \\ \text{bit prob of error for BEC} \end{matrix}$$

Typical behavior that we expect (say (3,6) ensemble)



(In exercises only formulas for EXIT are discussed).



Goal: show that Averaged form of Bethe free energy  
min allows to compute MAP performance curve. Since  
 stat pts of Bethe are fixed pts of BP equations  
 we will see that BP & MAP performance curves are  
 intimately related.

Bethe expression for coding; fixed code, fixed channel output.

Take Bethe expression of last time and adapt it to the  
 graphical model of coding. You get the functional:

$$\bar{F}_{\text{Bethe}} [h_{j \rightarrow a}, h_{a \rightarrow i}] = \bar{F}_a + \bar{F}_i - \bar{F}_{ai}$$

$$\bar{F}_a = \ln \left\{ 1 + \prod_{j \in \partial a} \tanh h_{j \rightarrow a} \right\}$$

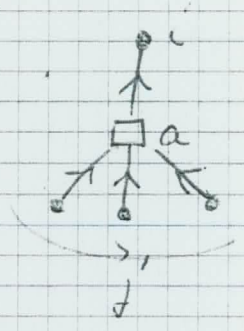
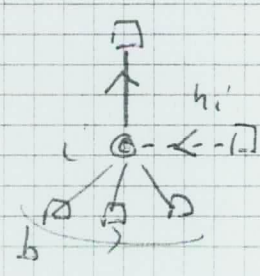
$$\bar{F}_i = \ln \left\{ e^{h_i} \prod_{a \in \partial i} (1 + \tanh h_{a \rightarrow i}) + e^{-h_i} \prod_{a \in \partial i} (1 - \tanh h_{a \rightarrow i}) \right\}$$

$$\bar{F}_{ai} = \ln \left\{ 1 + (\tanh h_{i \rightarrow a}) (\tanh h_{a \rightarrow i}) \right\}$$

(up to a constant proportional to  $\ln 2$ ).

Note that stat points of Bethe functional satisfy BE fixed point equations:

$$\begin{cases}
 h_{i \rightarrow a} = h_i + \sum_{b \in \partial i} \hat{h}_{b \rightarrow i} \\
 \hat{h}_{a \rightarrow i} = \text{atanh} \left\{ \prod_{j \in \partial a} \tanh h_{j \rightarrow a} \right\}
 \end{cases}$$



Replica Symmetric or Trial free energy/entropy:

- Take code (graph from  $\mathcal{CPC}(l, r)$ ) of random.
- Take r.v  $H \sim c(h)$  (channel output r.v).
- Take i.i.d  $H_1, \dots, H_n \sim Q(h)$  where  $Q(h)$  is a "trial" distribution to be fixed later.

• Define r.v 
$$\hat{H} = \text{atanh} \left( \prod_{j=1}^n \tanh H_j \right)$$

and form  $\hat{H}_1, \dots, \hat{H}_\ell$  i.i.d copies.

These are distr  $\sim \hat{Q}(\hat{h})$  which depends on  $Q(\cdot)$ .



Define counts correctly nb of checks.

$$\int_{\mathcal{B}^k} \mathcal{P}[H, \hat{H}] = \frac{1}{2} \ln \left\{ 1 + \prod_{j=1}^d \tanh H_j \right\}$$

← multiplied by  $\frac{1}{2}$ .

$$+ \frac{1}{2} \ln \left\{ e^{\frac{1}{2} \sum_{a=1}^d \frac{1}{\prod_{i=1}^d (1 + \tanh H_{a,i})} + e^{-\frac{1}{2} \sum_{a=1}^d \frac{1}{\prod_{i=1}^d (1 + \tanh H_{a,i})}} \right\}$$

$$- \frac{1}{2} \ln \left( 1 + (\tanh H) (\tanh \hat{H}) \right)$$

(counts correctly nb of edges)

Definition. The RS or Titch free energy / entropy is the functional of  $Q(\cdot)$ :

$$f_{RS}(Q(\cdot)) = \overline{\mathbb{E}}_{\text{LDPC}} \overline{\mathbb{E}}_{h, H, \hat{H}} \left\{ \int_{\mathcal{B}^k} \mathcal{P}[H, \hat{H}] \right\}$$

Note that case if LDPC is regular (say 3,6) the  $\overline{\mathbb{E}}_{\text{LDPC}}$  is trivial. Otherwise it is an average over local degrees of nodes ( $l, r$  are random).

In the entropy we have

$$h_{RS}(Q(\cdot)) = - f_{RS}(Q(\cdot)) - \int dh h c(h)$$

2. Conjecture: relation between BP & MAP

definition:  $f_{\text{exact}} \equiv \lim_{n \rightarrow +\infty} -\frac{1}{n} \overline{\log} \overline{E}_h (L^{\text{RS}}(h_n))$

conjecture:  $f_{\text{exact}} = \min_{Q(\cdot)} f_{\text{RS}}(Q(\cdot))$

or equivalently:

$$\lim_{n \rightarrow +\infty} -\frac{1}{n} \overline{\log} (H(\vec{x} | \vec{y})) = \max_{Q(\cdot)} (h_{\text{RS}}(Q(\cdot)))$$

$$= -\min_{Q(\cdot)} (f_{\text{RS}}(Q(\cdot)) - \int dh h dQ)$$

Formal stationary points are solutions of density evolution

fixed point equations.

$$\left\{ \begin{aligned} Q(\hat{H}) &= \int \prod_j Q(H_j) \delta(\hat{H} - \text{atanh} \prod_{j=1}^{b-1} \text{tanh} H_j) \\ Q(H) &= \int \text{atanh} \prod_{i=1}^b \hat{Q}(H_i) \delta(H - (h + \hat{H}_1 + \dots + \hat{H}_{b-1})) \end{aligned} \right.$$

To get the correct entropy we have to select the correct  
 stat pt (the one that yields a global minimum  
 maximum).



Main rigorous results:

\* upper / lower bound :

$$P_{\text{exact}} \leq \min_{q(\cdot)} I_{RS}(q(\cdot))$$

$$\text{or } \lim_{n \rightarrow \infty} \frac{1}{n} \log (H(\hat{x}|\hat{y})) \geq \max_{q(\cdot)} h_{RS}(q(\cdot))$$

(Proof by "interpolation method")

\* Equality for LDPC codes for high noise.

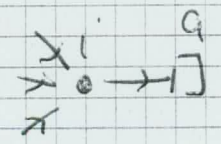
\* Equality for LDPC over the BEC ; ideas will be developed by Forney

3. Explicit case of BEC.

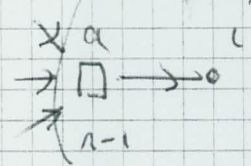
From analysis of BL equations for the BEC we know that:

c(h) = e f(h) + (1-e) Δ∞(h) (channel bw)

Q(H) = x f(H) + (1-x) Δ∞(H)
↑
prob of erasure message from



q(H) = x̂ f(H) + (1-x̂) Δ∞(H)
↑
prob of erasure message from



We must have x̂ = 1 - (1-x)^(n-1)
prob at least one incoming message is 'erasure'

and x is the 'trial' variable parametrizing

f\_RS(x) or h\_RS(x).

We have

h\_RS(x) = E\_{h,H,H} [ l/2 ln(1 + sum\_{j=1}^n tan H\_j) ] (a)

+ E\_{h,H,H} [ ln( sum\_{a=1}^l (1+tan H\_a) + e^{-2h} sum\_{a=1}^l (1-tan H\_a) ) ] (b)

= E\_{h,H,H} [ l ln(1 + tan H tan H) ] (c)



Term (a) :

$$\frac{l}{2} (1-x)^2 \ln 2$$

Term (c) :

$$- l (1-x)(1-\hat{x}) \ln 2$$

Term (b) :

$$(1-\epsilon) \sum_{\bar{E}=0}^l \binom{l}{\bar{E}} \hat{x}^{\bar{E}} (1-\hat{x})^{l-\bar{E}} \ln(2^{l-\bar{E}})$$

(h=1)

$$+ \epsilon \sum_{\bar{E}=0}^{l-1} \binom{l}{\bar{E}} \hat{x}^{\bar{E}} (1-\hat{x})^{l-\bar{E}} \ln(2^{l-\bar{E}}) \text{ "at least one non-erasure"}$$

(h=0)

$$+ \epsilon \binom{l}{l} \hat{x}^l (1-\hat{x})^{l-l} \ln 2 \text{ "all erasures"}$$

$$= \left\{ \sum_{\bar{E}=0}^l \binom{l}{\bar{E}} \hat{x}^{\bar{E}} (1-\hat{x})^{l-\bar{E}} (l-\bar{E}) \right\} \ln 2 + \epsilon \hat{x}^l \ln 2$$

$$(1-\hat{x}) \sum_{\bar{E}=0}^l \binom{l}{\bar{E}} \hat{x}^{\bar{E}} \frac{d}{dy} y^{l-\bar{E}} \Big|_{y=1-\hat{x}}$$

$$= (1-\hat{x}) \frac{d}{dy} (\hat{x} + y)^l \Big|_{y=1-\hat{x}} - (1-\hat{x}) \cdot l$$

So one finds (in units of  $l_2$ ):

$$h_{RS}(x) = \left\{ \frac{l}{2} (1-x)^2 \right\} + \left\{ \epsilon x^{\lambda} + l(1-x) \right\} - \left\{ l(1-x)(1-\hat{x}) \right\} - \frac{l}{2}$$

*comes from all other  $l_2$ 's.*

$$\Rightarrow h_{RS}(x) = + l x (1-\hat{x}) + \frac{l}{2} (1-x)^2 + \epsilon x^{\lambda} - \frac{l}{2}$$

with  $\hat{x} = 1 - (1-x)^{2-1}$ .

Stationary pts:

$$\frac{d}{dx} h_{RS}(x) = 0 \Rightarrow \frac{\partial}{\partial x} h_{RS} + \frac{\partial}{\partial \hat{x}} h_{RS} \cdot \frac{d\hat{x}}{dx} = 0$$

$$\Rightarrow \left( l(1-\hat{x}) - l(1-x)^{2-1} \right) + \left( -lx + \epsilon l x^{\lambda-1} \right) \cdot (2-1) \cdot (1-x)^{2-2} = 0$$

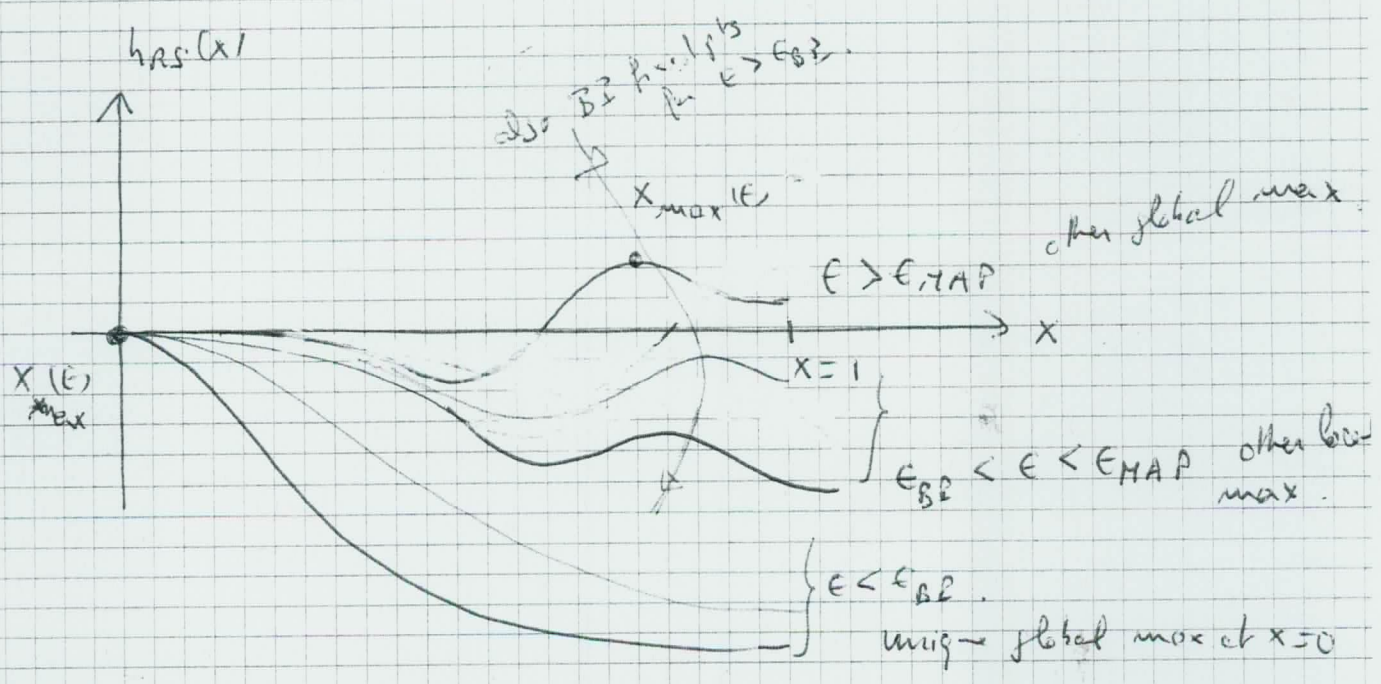
$$\Rightarrow \left( -lx + \epsilon l (1 - (1-x)^{2-1})^{\lambda-1} \right) \cdot (2-1) (1-x)^{2-2} = 0$$

$$\Rightarrow x = \epsilon (1 - (1-x)^{2-1})^{\lambda-1}$$

usual DF equation for measure probability.



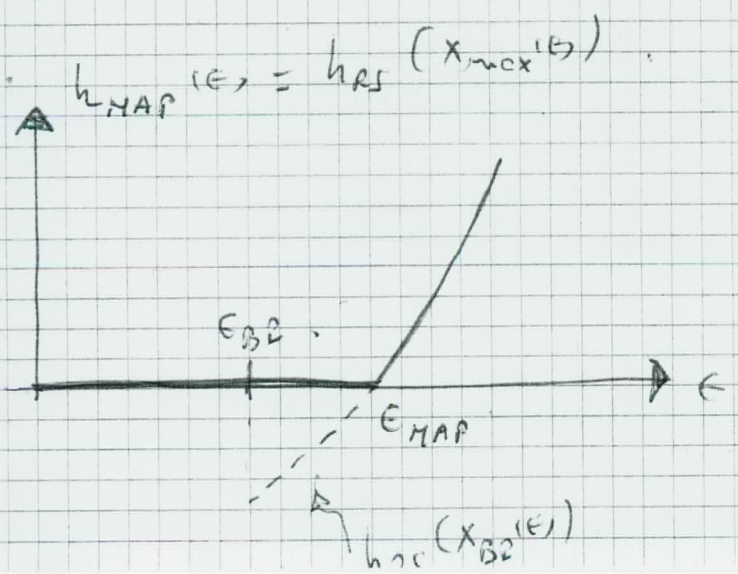
Pbt of  $h_{RS}(x)$  as a fct of  $x$  for fixed  $\epsilon$ .



$\epsilon < \epsilon_{B2}$        $x_{max}(E) = 0$       unique max

$\epsilon_{B2} < \epsilon < \epsilon_{MAP}$        $x_{max}(E) = 0$  / global max  
 $x_{B2}(E) \neq 0$  / local max

$\epsilon_{MAP} < \epsilon$        $x_{max}(E) \neq 0$  / global max  
 $x_{BP}(E) = 0$  / local max



MAP conditional entropy is:

$$h_{MAP}(\epsilon) = \max_{0 \leq x \leq 1} h_{RS}(x) = h_{RS}(x_{max}(\epsilon)),$$

where  $x_{max}(\epsilon)$  satisfies  $x = \epsilon (1 - (1-x)^{2-1})^{1-1}$ .

There is a close analogy with CW model:

$$\left\{ \begin{array}{l}
 p_{CW} = \min_m \phi(m) = \phi(m_{min}) \quad (\text{lecture 3}) \\
 \phi(m) = \left( -\frac{K}{2} m^2 - h m \right) - \underbrace{H_2(m)}_{\text{binary entropy fun.}} \\
 m_{min} \text{ satisfies } m = \text{tanh}(Km + h),
 \end{array} \right.$$

Probability of error.

MAP: Av Prob of bit error =  $\epsilon \frac{d}{d\epsilon} h_{MAP}(\epsilon)$   
 (see exercises no 4 or 5)

$$\frac{d}{d\epsilon} h_{MAP} = \underbrace{\frac{\partial}{\partial \epsilon} h_{RS}(x_{max}(\epsilon))}_{\neq 0} + \underbrace{\frac{\partial}{\partial x_{max}} h_{RS}}_0 \cdot \frac{dx_{max}}{d\epsilon}.$$

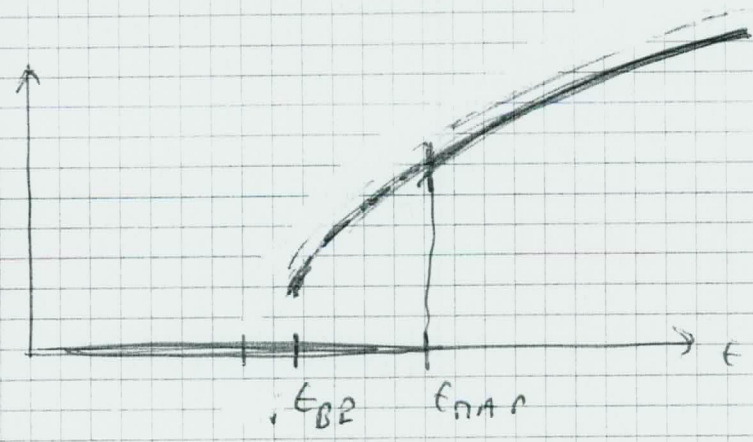
(away from threshold)

$$= \left( 1 - (1 - x_{max}(\epsilon))^{2-1} \right)^{1-1}.$$



So we get for NAP decoding (\*)

$$\text{Prob bit error} = E \left( 1 - (1 - x_{\max}(E))^{2-1} \right)^L$$



Since for  $E < E_{BP}$  &  $E > E_{NAP}$  we have

$x_{\max}(E)$  is the same than iterative sol  $x_{BP}(E)$

The BP & NAP curves are equal.

for  $E_{BP} < E < E_{NAP}$ ;  $x_{\max}(E) \neq x_{BP}(E)$

and BP curve is an extension of NAP curve.

⊗ Compare with

$$\text{Prob bit error for BP decoding} = E \left( 1 - (1 - x_{BP}(E))^{2-1} \right)^L$$