ÉCOLE POLYTECHNIQUE FÉDÉRALE DE LAUSANNE

School of Computer and Communication Sciences

Handout 11

Principles of Digital Communications

Solutions to Problem Set 5

Mar. 24, 2015

SOLUTION 1.

(a) Let the two hypotheses be H=0 and H=1 when c_0 and c_1 are transmitted, respectively. The ML decision rule is

$$f_{Y_1Y_2|H}(y_1, y_2|1) \stackrel{\hat{H}=1}{\underset{\hat{H}=0}{\geq}} f_{Y_1Y_2|H}(y_1, y_2|0).$$

Because Z_1 and Z_2 are independent, we can write

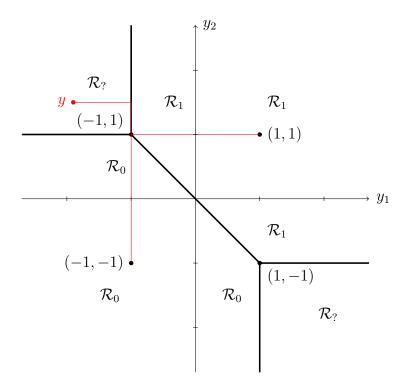
$$\frac{1}{2}e^{-|y_1-1|}\frac{1}{2}e^{-|y_2-1|} \mathop{\stackrel{\hat{H}=1}{\underset{\hat{H}=0}{\geq}}} \frac{1}{2}e^{-|y_1+1|}\frac{1}{2}e^{-|y_2+1|},$$

and, after taking the logarithm,

$$|y_1+1|+|y_2+1| \stackrel{\hat{H}=1}{\underset{\hat{H}=0}{\geq}} |y_1-1|+|y_2-1|.$$

(b) Because the hypotheses are equally likely and Z_1 and Z_2 have the same distribution, the decision region for $\hat{H} = 0$ contains the points closer to (-1, -1) and the decision region for $\hat{H} = 1$ contains the points closer to (1, 1). For this problem, the distance between the points (y_{11}, y_{12}) and (y_{21}, y_{22}) is the Manhattan distance, $|y_{11} - y_{21}| + |y_{12} - y_{22}|$, and not the Euclidean distance.

Let us first consider the points above the line $y_2 = -y_1$. It is easy to notice that the points in the positive quadrant are closer to (1,1) than to (-1,-1), therefore they belong to \mathcal{R}_1 $(\hat{H}=1)$. This is also true if $\{(y_1 \geq 0) \cap (y_2 \in (-1,0))\}$, or if $\{(y_2 \geq 0) \cap (y_1 \in (-1,0))\}$.



Similar reasoning can be applied to the points below the diagonal to determine \mathcal{R}_0 . The points for which $\{(y_1 \leq -1) \cap (y_2 \geq 1)\}$ or $\{(y_1 \geq 1) \cap (y_2 \leq -1)\}$ are equally distanced to (-1, -1) and (1, 1), therefore they can belong to either \mathcal{R}_0 or \mathcal{R}_1 with the same probability. This region is named \mathcal{R}_2 .

(c) The two hypotheses are equally probable for the region $\mathcal{R}_{?}$. Therefore, we can split this region in any way between the decision regions and have the same error probability. Because \mathcal{R}_{1} is included in the region for which $y_{2} > -y_{1}$ and \mathcal{R}_{0} does not intersect the region for which $y_{2} > -y_{1}$, the error probability is minimized by deciding $\hat{H} = 1$ if $(y_{1} + y_{2}) > 0$.

(d)

$$P_{e}(0) = \Pr \{Y_{1} + Y_{2} > 0 | H = 0\}$$

$$= \Pr \{Z_{1} + Z_{2} - 2 > 0\}$$

$$= \int_{2}^{\infty} \frac{e^{-w}}{4} (1 + w) dw$$

$$= \frac{-e^{-w}}{4} (w + 2)|_{2}^{\infty} = e^{-2}.$$

By symmetry, and considering that the messages are equally likely, $P_e(0) = P_e(1) = P_e$.

Solution 2. We start by normalizing β_1 :

$$\|\beta_1\| = \sqrt{\langle \beta_1, \beta_1 \rangle} = \sqrt{3}$$

 $\psi_1 = \frac{\beta_1}{\|\beta_1\|} = (\frac{1}{\sqrt{3}}, 0, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}).$

We get the next basis vectors as follows:

$$\langle \psi_1, \beta_2 \rangle = \sqrt{3}$$

$$\phi_2 = \beta_2 - \sqrt{3}\psi_1 = (1, 1, -1, 0)$$

$$\|\phi_2\| = \sqrt{3}$$

$$\psi_2 = \frac{\phi_2}{\|\phi_2\|} = (\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, -\frac{1}{\sqrt{3}}, 0).$$

We compute

$$\langle \psi_1, \beta_3 \rangle = 0$$

 $\langle \psi_2, \beta_3 \rangle = 0.$

Thus,

$$\phi_3 = \beta_3 - 0\psi_1 - 0\psi_2 = (1, 0, 1, -2)$$
$$\|\phi_3\| = \sqrt{1 + 1 + 4} = \sqrt{6}$$
$$\psi_3 = \frac{\phi_3}{\|\phi_3\|} = (\frac{1}{\sqrt{6}}, 0, \frac{1}{\sqrt{6}}, -\frac{2}{\sqrt{6}}).$$

We proceed similarly to obtain ϕ_4 :

$$\langle \psi_1, \beta_4 \rangle = \sqrt{3}$$

$$\langle \psi_2, \beta_4 \rangle = 0$$

$$\langle \psi_3, \beta_4 \rangle = \sqrt{6}$$

$$\phi_4 = \beta_4 - \sqrt{3}\psi_1 - 0\psi_2 - \sqrt{6}\psi_3 = (0, 0, 0, 0).$$

As can be seen, the last vector is zero. This shows that the dimensionality of the space spanned by β_1, \dots, β_4 is only 3, not 4. So the other benefit of Gram-Schmidt orthogonalization is that it gives us the dimension of the space spanned by the initial vectors.

SOLUTION 3.

(a) We use the Gram-Schmidt procedure:

(i) The first step is to normalize the function $\beta_0(t)$, i.e. the first function of the basis that we are looking for is

$$\psi_0(t) = \frac{\beta_0(t)}{\|\beta_0(t)\|} = \frac{\beta_0(t)}{\sqrt{\int \beta_0(t)^2 dt}}$$

$$= \frac{\beta_0(t)}{\sqrt{\int_0^1 4t^2 dt}} = \frac{\sqrt{3}}{2}\beta_0(t) = \begin{cases} 0, & \text{if } t < 0\\ \sqrt{3}t, & \text{if } 0 \le t \le 1\\ 0, & \text{if } t > 1 \end{cases}.$$

(ii) Next, we subtract from $\beta_1(t)$ the components that are in the span of the currently established part of the basis, i.e. in the span of $\{\psi_0(t)\}$. This can be achieved by projecting $\beta_1(t)$ onto $\psi_0(t)$ and then subtracting this projection from $\beta_1(t)$, i.e.

$$\alpha_1(t) = \beta_1(t) - \langle \beta_1(t), \psi_0(t) \rangle \psi_0(t) = \beta_1(t) - \left(\int \beta_1(t) \psi_0(t) \, dt \right) \psi_0(t)$$

$$= \beta_1(t) - \left(\frac{\sqrt{3}}{2} \right) \left(\frac{4}{3} \right) \psi_0(t)$$

$$= \beta_1(t) - \frac{2}{\sqrt{3}} \psi_0(t)$$

$$= \beta_1(t) - \beta_0(t).$$

From this, we find the second basis element as

$$\psi_1(t) = \frac{\alpha_1(t)}{||\alpha_1(t)||} = \begin{cases} 0, & \text{if } t < 1\\ -\sqrt{3}(t-2), & \text{if } 1 \le t \le 2\\ 0, & \text{if } t > 2 \end{cases}.$$

(iii) Again, we subtract from $\beta_2(t)$ the components that are in the span of the currently established part of the basis, i.e. in the span of $\{\psi_0(t), \psi_1(t)\}$. This can be achieved by projecting $\beta_2(t)$ onto $\psi_0(t)$ and $\psi_1(t)$ and then subtracting both these projections from $\beta_2(t)$. For this step, it is *essential* that the basis elements $\{\psi_0(t), \psi_1(t)\}$ be orthonormal. Make sure you understand why. Continuing the derivation, we obtain

$$\alpha_{2}(t) = \beta_{2}(t) - \langle \beta_{2}(t), \psi_{0}(t) \rangle \psi_{0}(t) - \langle \beta_{2}(t), \psi_{1}(t) \rangle \psi_{1}(t)$$

$$= \beta_{2}(t) - \left(\int \beta_{2}(t) \psi_{0}(t) \ dt \right) \psi_{0}(t) - \left(\int \beta_{2}(t) \psi_{1}(t) \ dt \right) \psi_{1}(t)$$

$$= \beta_{2}(t) - 0 - \alpha_{1}(t)$$

$$= \beta_{2}(t) + \beta_{0}(t) - \beta_{1}(t),$$

and from this, we find the third basis element as

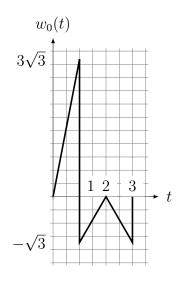
$$\psi_2(t) = \frac{\alpha_2(t)}{||\alpha_2(t)||} = \begin{cases} 0, & \text{if } t < 2\\ -\sqrt{3}(t-2), & \text{if } 2 \le t \le 3\\ 0, & \text{if } t > 3 \end{cases}.$$

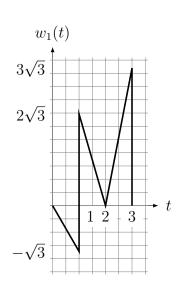
(b) By definition we can write $w_0(t)$ and $w_1(t)$ as follows

$$w_0(t) = 3\psi_0(t) - \psi_1(t) + \psi_2(t) = \begin{cases} 3\sqrt{3}t, & \text{if } 0 \le t < 1\\ \sqrt{3}(t-2), & \text{if } 1 < t < 2\\ -\sqrt{3}(t-2), & \text{if } 2 < t \le 3 \end{cases}$$

and

$$w_1(t) = -\psi_0(t) + 2\psi_1(t) + 3\psi_2(t) = \begin{cases} -\sqrt{3}t, & \text{if } 0 \le t < 1\\ -2\sqrt{3}(t-2), & \text{if } 1 < t < 2\\ -3\sqrt{3}(t-2), & \text{if } 2 < t \le 3 \end{cases}$$





(c)

$$\langle c_0, c_1 \rangle = -3 \cdot 1 - 1 \cdot 2 + 1 \cdot 3 = -2.$$

We know that $w_0(t)$ and $w_1(t)$ are both real, thus

$$\langle w_0(t), w_1(t) \rangle = \int w_0(t)w_1(t) dt = \int_0^1 -9t^2 dt + \int_1^2 -6(t-2)^2 dt + \int_2^3 9(t-2)^2 dt$$

= $-\int_1^2 6(t-2)^2 dt = -2$.

We see that the inner products are equal as expected.

(d)

$$||c_0|| = \sqrt{\langle c_0, c_0 \rangle} = \sqrt{11},$$

 $||w_0||^2 = \int |w_0(t)|^2 dt = \int_0^1 27t^2 dt + \int_1^3 3(t-2)^2 dt = 9 + 2 = 11.$

We see that the norms are also equal.

Solution 4.

(a) $||q_i|| = \sqrt{T}, \quad i = 1, 2, 3.$

(b) Z_1 and Z_2 are independent since g_1 and g_2 are orthogonal. Hence Z is a Gaussian random vector $\sim \mathcal{N}(0, \sigma^2 I_2)$, where $\sigma^2 = \frac{N_0}{2}T$.

(c)

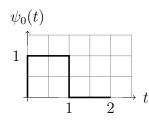
$$P_{a} = \Pr \{ Z_{1} \in [1, 2] \cap Z_{2} \in [1, 2] \} = \Pr \{ Z_{1} \in [1, 2] \} \Pr \{ Z_{2} \in [1, 2] \}$$
$$= \left[Q \left(\frac{1}{\sigma} \right) - Q \left(\frac{2}{\sigma} \right) \right]^{2},$$

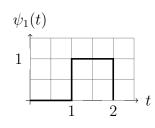
where $\sigma^2 = \frac{N_0}{2}T$.

- (d) $P_b = P_a$, since one obtains the square (b) from the square (a) via a rotation.
- (e) $Z_3 = -Z_1$. $U = Z_1(1, -1)^\mathsf{T}$, and thus U can never be in (a), hence $Q_a = 0$.
- (f) U is in square (c) if and only if $Z_1 \in [1,2]$. Hence $Q_c = Q\left(\frac{1}{\sigma}\right) Q\left(\frac{2}{\sigma}\right)$, where $\sigma^2 = \frac{N_0}{2}T$.

SOLUTION 5.

(a) An orthonormal basis for the signal space spanned by the waveforms is 1:





¹this can be obtained using Gram-Schmidt procedure or simply by looking at the waveforms

(b) The codewords representing the waveforms are

$$c_0 = (\sqrt{\mathcal{E}}, 0)$$

$$c_1 = (-\sqrt{\mathcal{E}}, 0)$$

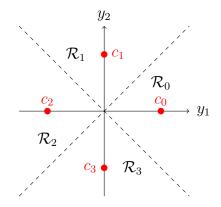
$$c_2 = (0, \sqrt{\mathcal{E}})$$

$$c_3 = (0, -\sqrt{\mathcal{E}})$$

(c) As we have seen in the lecture, if R(t) is the noisy received waveform, $(Y_0, Y_1) = (\langle R, \psi_0 \rangle, \langle R, \psi_1 \rangle)$ is a sufficient statistic for decision. Hence, we have the following hypothesis testing problem: Under H = i, i = 0, 1, 2, 3,

$$Y_i = c_i + Z,$$

where $Z \sim \mathcal{N}(0, \frac{N_0}{2}I_2)$. One can check that c_i , i = 0, 1, 2, 3 represent the QPSK codewords (and as we have seen in Homework 3) the decision regions for the ML receiver will be as follows:



The distance between two adjacent codewords (say c_0 and c_1) is $d = \sqrt{2\mathcal{E}}$ and the probability of error of the receiver is

$$P_e = 2Q \left(\frac{d}{2\sigma}\right) - Q^2 \left(\frac{d}{2\sigma}\right)$$

$$= 2Q \left(\frac{\sqrt{2\mathcal{E}}}{2\sqrt{N_0/2}}\right) - Q^2 \left(\frac{\sqrt{2\mathcal{E}}}{2\sqrt{N_0/2}}\right)$$

$$= 2Q \left(\sqrt{\frac{\mathcal{E}}{N_0}}\right) - Q^2 \left(\sqrt{\frac{\mathcal{E}}{N_0}}\right).$$