

Solution de la série 9 Traitement quantique de l'information II

Exercice 1 *Refocusing*

L'état final est

$$\begin{aligned} e^{-\frac{it}{\hbar}\mathcal{H}}|\psi_0\rangle &= e^{-itJ\sigma_1^z\otimes\sigma_2^z} \cdot \frac{1}{2} (|\uparrow\uparrow\rangle - |\uparrow\downarrow\rangle + |\downarrow\uparrow\rangle - |\downarrow\downarrow\rangle) \\ &= \frac{1}{2} (e^{-itJ} |\uparrow\uparrow\rangle - e^{itJ} |\uparrow\downarrow\rangle + e^{itJ} |\downarrow\uparrow\rangle - e^{-itJ} |\downarrow\downarrow\rangle) \\ &= \frac{e^{-itJ}}{2} (|\uparrow\uparrow\rangle - e^{2itJ} |\uparrow\downarrow\rangle + e^{2itJ} |\downarrow\uparrow\rangle - |\downarrow\downarrow\rangle). \end{aligned}$$

– Pour $t = \frac{\pi}{4J}$ on a $e^{2itJ} = e^{\frac{i\pi}{2}} = i$

$$\Rightarrow |\psi_\tau\rangle = \frac{e^{-\frac{i\pi}{4}}}{2} (|\uparrow\uparrow\rangle - i|\uparrow\downarrow\rangle + i|\downarrow\uparrow\rangle - |\downarrow\downarrow\rangle).$$

– Supposons que l'état puisse s'écrire

$$(\alpha|\uparrow\rangle + \beta|\downarrow\rangle) \otimes (\gamma|\uparrow\rangle + \delta|\downarrow\rangle) = \alpha\gamma|\uparrow\uparrow\rangle + \alpha\delta|\uparrow\downarrow\rangle + \beta\gamma|\downarrow\uparrow\rangle + \beta\delta|\downarrow\downarrow\rangle,$$

alors $\alpha\gamma = 1$, $\alpha\delta = -i$, $\beta\gamma = i$, $\beta\delta = -1$.

On peut toujours poser $\alpha = 1$ (phase globale). Donc $\gamma = 1$, $\delta = -i$, $\beta = i$ et $\delta = i \Rightarrow$ contradiction sur δ . Vous pouvez aussi prendre n'importe quelle valeur fixée pour α et montrer qu'une contradiction apparait.

Exercice 2 *Refocusing*

– One way is to find the corresponding matrices and multiply them together to show the identity. A probably simpler way is to show that for every basis vector both right hand side and left hand side operators give the same result. For example for $|\psi_0\rangle = |\uparrow\uparrow\rangle$, applying the matrices starting from the right hand side one, one obtains (using that R_1 flips a spin; check this!)

$$\begin{aligned} |\psi_1\rangle &= e^{-i\frac{t}{2}\frac{\mathcal{H}}{\hbar}} |\uparrow\uparrow\rangle = e^{-itJ} |\psi_0\rangle, \\ |\psi_2\rangle &= (R_1 \otimes I) |\psi_1\rangle = e^{-itJ} |\downarrow\uparrow\rangle, \\ |\psi_3\rangle &= e^{-i\frac{t}{2}\frac{\mathcal{H}}{\hbar}} |\psi_2\rangle = e^{-itJ} e^{-i\frac{t}{2}\frac{\mathcal{H}}{\hbar}} |\downarrow\uparrow\rangle = e^{-itJ} e^{itJ} |\downarrow\uparrow\rangle = |\downarrow\uparrow\rangle, \\ |\psi_4\rangle &= (R_1 \otimes I) |\psi_3\rangle = (R_1 \otimes I) |\downarrow\uparrow\rangle = |\uparrow\uparrow\rangle, \end{aligned}$$

which shows that $|\psi_4\rangle = |\psi_0\rangle = (I_1 \otimes I_2) |\psi_0\rangle$. One can also check this for other basis vectors to see that the identity indeed holds.

- $J \ll 1$. Donc $\tau = \frac{\pi}{4J} \gg \pi$. Les π -pulses sont beaucoup plus rapides que l'évolution des spins nucléaires. L'idée est que en injectant deux π -pulses aux instants $\frac{\tau}{2}$ et τ on reforme l'état initial et donc tout se passe comme si les deux spins n'avaient pas évolué.

Exercice 3 *Realization of the SWAP port*

- To find the matrix representation, it is sufficient to find how SWAP port operates on the basis vectors.

$$\text{SWAP} |\uparrow\uparrow\rangle = |\uparrow\uparrow\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix},$$

$$\text{SWAP} |\uparrow\downarrow\rangle = |\downarrow\uparrow\rangle = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix},$$

$$\text{SWAP} |\downarrow\uparrow\rangle = |\uparrow\downarrow\rangle = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix},$$

$$\text{SWAP} |\downarrow\downarrow\rangle = |\downarrow\downarrow\rangle = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}.$$

Putting the resulting columns together we obtain the matrix representation

$$\text{SWAP} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}.$$

Now it is easy to check that $(\text{SWAP})(\text{SWAP}^\dagger) = I$ which shows that SWAP is a unitary matrix.

- The Heisenberg Hamiltonian is obtained in the lecture notes and has the following matrix representation

$$\mathcal{H} = \hbar J \vec{\sigma}_1 \cdot \vec{\sigma}_2 = \hbar J \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 2 & 0 \\ 0 & 2 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}.$$

To compute the evolution operator $e^{-\frac{i\mathcal{H}\tau}{\hbar}}$, we notice that the matrix for \mathcal{H} has the diagonal representation

$$\begin{pmatrix} A & \mathbf{0} \\ \mathbf{0} & B \\ & & C \end{pmatrix},$$

where $A = (1)$ and $C = (1)$ are 1×1 matrices and $B = \begin{pmatrix} -1 & 2 \\ 2 & -1 \end{pmatrix}$ is a 2×2 matrix. It is easy to show that for any complex number α

$$e^{\alpha \mathcal{H}} = \begin{pmatrix} e^{\alpha A} & & \mathbf{0} \\ & e^{\alpha B} & \\ \mathbf{0} & & e^{\alpha C} \end{pmatrix}.$$

Thus it is sufficient to find these three matrix exponentials. A and C are numbers equal to 1, thus $e^{\alpha A} = e^{\alpha C} = e^\alpha$.

Now it remains to find $e^{\alpha B}$. Notice that we can write $B = -I + 2X$ where $X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$.

Notice that I and X commute with each other, i.e., $IX = XI$. It is not difficult to show that the matrices that commute with each other can be treated like numbers while taking exponentials, namely, for any commuting matrix M, N , $e^{M+N} = e^M e^N$. (**Notice that this formula is not in general correct**). Therefore, we have

$$e^{i\beta B} = e^{-i\beta I} e^{2i\beta X} = e^{-i\beta} (I \cos(2\beta) + iX \sin(2\beta)),$$

where we used the Euler's formula for X . It can be checked that at time $t = \frac{\pi}{4J}$, $\alpha = -i\frac{\pi}{4}$, thus $\beta = -\frac{\pi}{4}$. Hence, $e^{\alpha A} = e^{\alpha B} = e^{-i\frac{\pi}{4}}$, and

$$e^{i\beta B} = e^{i\frac{\pi}{4}} (\cos(\frac{\pi}{2})I - i \sin(\frac{\pi}{2})X) = -ie^{i\frac{\pi}{4}} X = e^{-i\frac{\pi}{4}} X.$$

Putting all together, the evolution operator at time $t = \frac{\pi}{4J}$ is

$$e^{-i\frac{\pi}{4}} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix},$$

which neglecting the constant phase $-\frac{\pi}{4}$ is equal to the matrix for SWAP.

- We can implement SWAP using three CNOT gates as depicted in Figure 1. To show this, one can simply check that starting from a general state $|x, y\rangle$, with $x, y \in \{0, 1\}$ after the first CNOT the resulting state is $|x, y \oplus x\rangle$, after the second CNOT the state is

$$|x \oplus (x \oplus y), x \oplus y\rangle = |x \oplus x \oplus y, x \oplus y\rangle = |y, x \oplus y\rangle,$$

where we used the identity $x \oplus x = 0$ for $x \in \{0, 1\}$. Finally after the third CNOT the state is $|y, (x \oplus y) \oplus y\rangle = |y, x\rangle$. Therefore the combination the three gates just swaps x and y .

Note that this gives another proof that SWAP is a unitary matrix because it can be implemented as a combination of quantum gates and we know that all quantum gates are unitary.

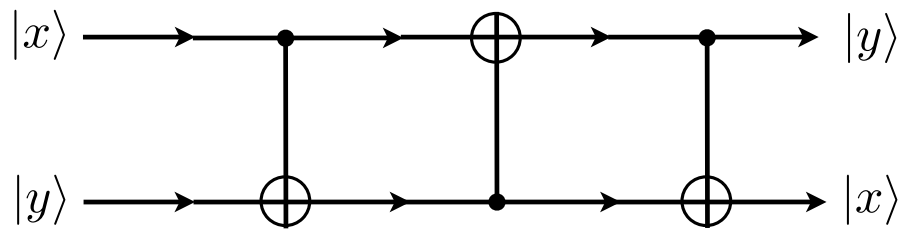


FIGURE 1 – Implementation of SWAP gate using three CNOT