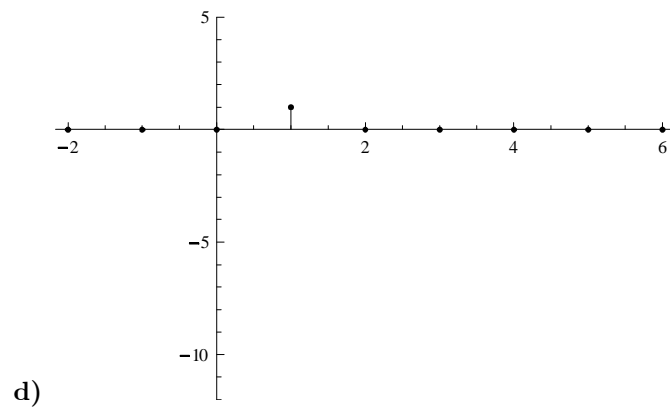
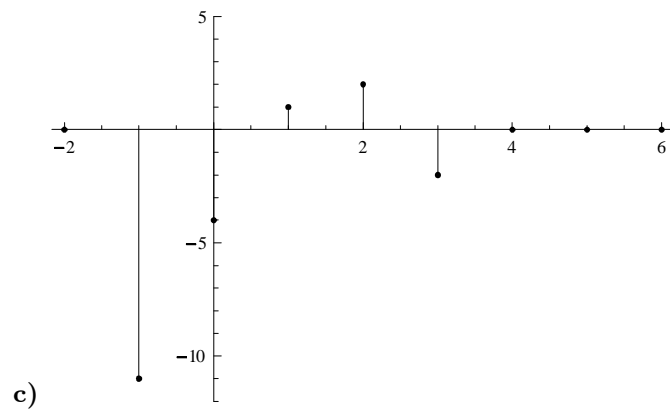
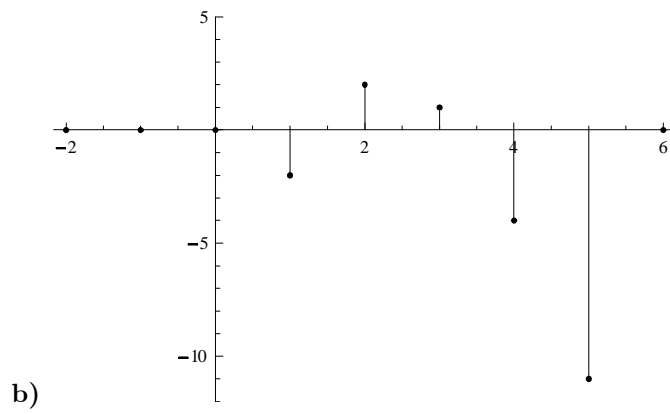
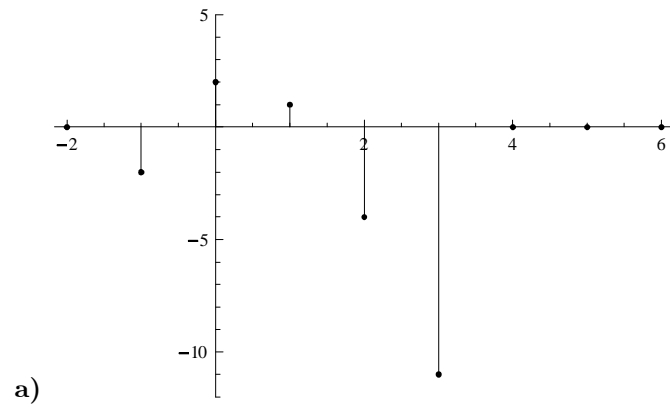
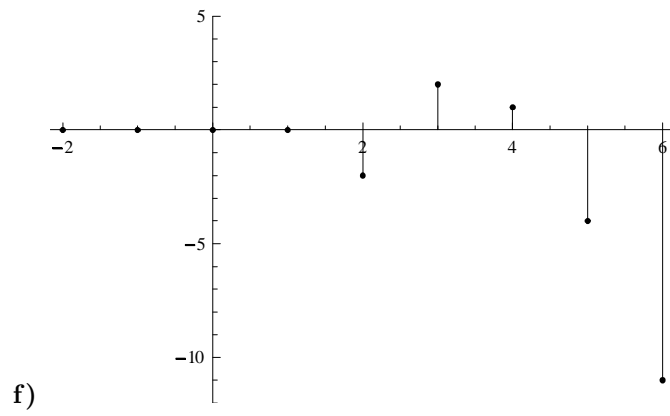
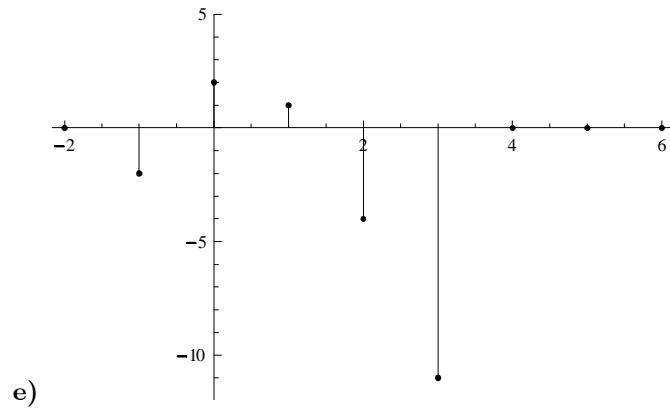
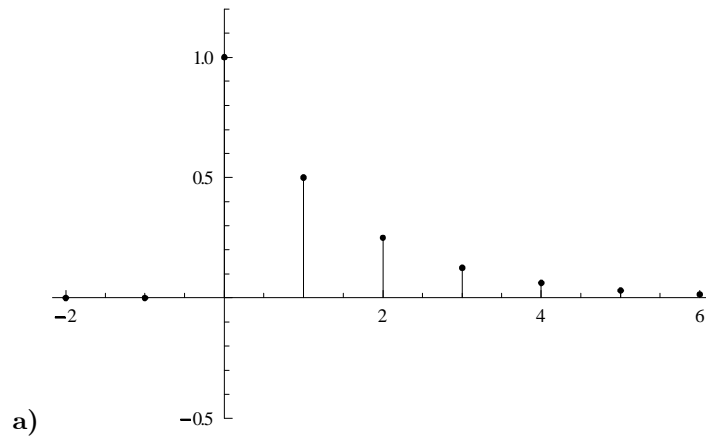


# Problem 1





## Problem 2



b) The system is causal because  $h(n) = 0$  for  $n < 0$ .

c)

$$\begin{aligned}(1-r) \sum_{k=0}^n r^k &= \sum_{k=0}^n r^k - r \sum_{k=0}^n r^k \\ &= \sum_{k=0}^n r^k - \sum_{k=0}^n r^{k+1} \\ &= \sum_{k=0}^n r^k - \sum_{k=1}^{n+1} r^k \\ &= r^0 + \sum_{k=1}^n r^k - \left( r^{n+1} + \sum_{k=1}^n r^k \right) \\ &= 1 - r^{n+1}\end{aligned}$$

d) The system is stable because

$$\begin{aligned}\sum_{k=-\infty}^{\infty} |h(k)| &= \sum_{k=0}^{\infty} 2^{-k} \\ &= \lim_{k \rightarrow \infty} \frac{1 - 2^{-(k+1)}}{1 - 2^{-1}} \\ &= 2 < \infty\end{aligned}$$

e)

$$\begin{aligned}\frac{d}{dr} \frac{1 - r^{n+1}}{1 - r} &= \frac{d}{dr} \sum_{k=0}^n r^k \\ &= \sum_{k=0}^n \frac{d}{dr} r^k \\ &= \sum_{k=0}^n k r^{k-1} \\ &= r^{-1} \sum_{k=0}^n k r^k\end{aligned}$$

f)

$$\begin{aligned}y(n) &= \sum_{k=-\infty}^{\infty} h(k) x(n-k) \\ &= \sum_{k=0}^{\infty} 2^{-k} (n-k) \\ &= n \sum_{k=0}^{\infty} 2^{-k} - \sum_{k=0}^{\infty} k 2^{-k} \\ &= 2n - 2 \frac{d}{dr} \left( \frac{1}{1-r} \right) \Big|_{r=2} \\ &= 2n - \frac{1}{2} \left( \frac{1}{(1-1/2)^2} \right) \\ &= 2(n-1)\end{aligned}$$

### Problem 3

We have a system from which we only know a linear time-invariant recurrence relation between the input  $x(n)$  and the output  $y(n)$ , namely

$$y(n+1) = y(n) + x(n)$$
$$\lim_{m \rightarrow -\infty} y(m) = 0$$

a)  $y(4) = y(3) + x(3) = y(2) + x(2) + x(3) = y(1) + x(1) + x(2) + x(3) = y(0) + x(0) + x(1) + x(2) + x(3)$

b) Since  $\lim_{m \rightarrow -\infty} y(m) = 0$

$$y(n) = \lim_{m \rightarrow -\infty} y(n)$$
$$= \lim_{m \rightarrow -\infty} \left( y(m) + \sum_{k=m}^{n-1} x(k) \right)$$
$$= \sum_{k=-\infty}^{n-1} x(k)$$

The output signal is a summation of the input signal.

c) For  $n < 0$ , since  $\delta(n) = 0$  then  $h(n+1) = h(n)$  and  $h(n+1) = 0$  if  $n < 0$ .  $h(1) = \delta(0) = 1$  and for  $n \geq 1$  since  $\delta(n) = 0$  then  $h(n+1) = h(n) = h(n-1) = \dots = h(1) = 1$ . We finally found that

$$h(n) = \begin{cases} 1 & \text{if } n \geq 1 \\ 0 & \text{otherwise} \end{cases} .$$

d) The general output is

$$y(t) = \sum_{k=-\infty}^{\infty} h(k) x(n-k)$$
$$= \sum_{k=1}^{\infty} x(n-k)$$
$$= \sum_{k=-\infty}^{-1} x(n+k)$$
$$= \sum_{k=-\infty}^{n-1} x(k)$$

This is same answer than the one found in b)

e) The system is unstable because  $\sum_{k=-\infty}^{\infty} |h(k)| = \sum_{k=1}^{\infty} 1 = \infty$ . An example of unstable input signal is  $x(n) \equiv 1$ .

### Problem 4

$$\sin(10\pi t) + \sin(30\pi t)$$

a) The maximum frequency between these two sinusoids is  $15Hz$ . So  $f_s > 30Hz$ .

b) If we use the sampling frequency  $f_s = 20Hz$ , what the sampled signal would be?

$$\begin{aligned}\sin\left(10\pi\frac{n}{20}\right) + \sin\left(30\pi\frac{n}{20}\right) &= \sin\left(\frac{\pi}{2}n\right) + \sin\left(\frac{3\pi}{2}n\right) \\ &= \sin\left(\frac{\pi}{2}n\right) + \sin\left(-\frac{\pi}{2}n\right) \\ &= \sin\left(\frac{\pi}{2}n\right) - \sin\left(\frac{\pi}{2}n\right) \\ &= 0\end{aligned}$$

c) The ideal filter will suppress all frequency greater than  $\frac{f_s}{2}$ . So the sampled signal would be

$$\sin\left(10\pi\frac{n}{20}\right) = \sin\left(\frac{\pi}{2}n\right)$$

d) The sampling frequency is  $f_s = 25Hz$  and we use an ideal interpolator. What the reconstructed signal would be? The first sinusoid is perfectly reconstructed because  $5Hz < \frac{25}{2}Hz$ , but the second one is altered. An alias frequency for  $15Hz$  and lying in the interval  $(-25/2, 25/2)$  is given by  $15 - 25 = -10Hz$ . Thus the reconstructed signal would be

$$\sin(10\pi t) - \sin(20\pi t)$$

## Problem 5

We have a continuous signal  $x(t)$  with a missing part between  $t = 1$  and  $t = -1$ . The signal is zero everywhere and the only information we know in the missing part is  $x(0) = 1$ . We want to interpolate this signal.

a) We have to solve two linear system of equation, one for  $\{x(-1), x(0)\}$  and an other for  $\{x(0), x(1)\}$ . For the first part we have

$$\begin{cases} -a + b = 0 \\ b = 1 \end{cases}$$

this gives  $a = 1$  and  $b = 1$ . For the second part we have

$$\begin{cases} a + b = 0 \\ b = 1 \end{cases}$$

and we have  $a = -1$  and  $b = 1$ .

b) We have to solve the following linear system of equation

$$\begin{cases} a - b + c = 0 \\ c = 1 \\ a + b + c = 0 \end{cases}$$

we find  $a = -1$ ,  $b = 0$  and  $c = 1$ .

c) Now we have two equations given by the derivatives i.e.  $3at^2 + 2bt + c$ . The system is

$$\begin{cases} -a + b - c + d = 0 \\ d = 1 \\ 3a - 2b + c = 0 \\ c = 1 \end{cases}$$

and we find  $a = -2$ ,  $b = -3$ ,  $c = 0$ ,  $d = 1$