
FINAL

Wednesday February 16, 2005, 14:15-17:15
This exam has 4 problems and 100 points in total.

Instructions

- You are allowed to use 2 sheets of paper for reference. No mobile phones or calculators are allowed in the exam.
- You can attempt the problems in any order as long as it is clear which problem is being attempted and which solution to the problem you want us to grade.
- If you are stuck in any part of a problem do not dwell on it, try to move on and attempt it later.

- The Q -function

$$Q(x) = \frac{1}{\sqrt{2\pi}} \int_x^\infty e^{-u^2/2} du,$$

and $Q(-x) = 1 - Q(x)$.

- $Q(x) \leq e^{-\frac{x^2}{2}}$.

- For a 2×2 matrix $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$,

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

- $\sum_{n=0}^{N-1} r^n = \frac{1-r^N}{1-r}$.

- You may find this property useful. If $h \sim \mathbf{CN}(0, 1)$,

$$\lim_{\delta \rightarrow 0} \left[\frac{1}{\delta} \text{Prob}(|h|^2 < \delta) \right] = 1.$$

This means that for *small* δ , $\text{Prob}(|h|^2 < \delta) \approx \delta$.

- You may find this lemma useful: If $U \sim \mathbf{CN}(0, \mathbf{K}_U)$, and $\mathbf{A} = \mathbf{A}^*$, for some $b \in \mathbf{C}$ then

$$\mathbf{E}_U [e^{-b\mathbf{U}^* \mathbf{A} \mathbf{U}}] = \frac{1}{|\mathbf{I} + b\mathbf{K}_U \mathbf{A}|}.$$

- There are also 5 bonus points to be had making the maximum number of points 105/100.

GOOD LUCK!

Problem 1

[NOISE CANCELLATION (15pts)]

Consider two individual scalar observations Y_1, Y_2 as,

$$\begin{aligned} Y_1 &= X + Z_1 \\ Y_2 &= Z_2, \end{aligned} \quad (1)$$

Assume that zero mean Z_1, Z_2 are independent of X and are correlated with covariance,

$$\mathbb{E}[\mathbf{Z}\mathbf{Z}^*] = \begin{bmatrix} \sigma^2 & \rho\sigma^2 \\ \rho^*\sigma^2 & \sigma^2 \end{bmatrix}, \quad (2)$$

where $\mathbf{Z} = [Z_1, Z_2]^T$. Let $\mathbb{E}[|X|^2] = \mathcal{E}_x$.

[5pts] (a) Find the best linear MMSE estimate of \hat{X} of the random variable X from the observations Y_1, Y_2 .

[5pts] (b) What is the minimum mean-squared error $\mathbb{E}[|X - \hat{X}|^2]$ of the best linear estimator? Is there a value of ρ for which we get $\mathbb{E}[|X - \hat{X}|^2] = 0$? Interpret the result if $\mathbb{E}[|X - \hat{X}|^2] = 0$ is possible.

[5pts] (c) Find the best estimate \hat{Z}_1 of the random variable Z_1 from Y_2 . Consider the operation

$$\tilde{Y}_1 = Y_1 - \hat{Z}_1$$

Find the best linear estimate of X from \tilde{Y}_1 . Is it the same as the answer you found in (a)? Do you have an interpretation?

Problem 2

[INTER-CARRIER INTERFERENCE IN OFDM (25pts)]

Consider the scalar discrete-time inter symbol interference channel considered in the class,

$$y_k = \sum_{n=0}^{\nu} p_n x_{k-n} + z_k, \quad k = 0, \dots, N-1, \quad (3)$$

where $z_k \sim \mathcal{CN}(0, \sigma_z^2)$ and is i.i.d., independent of $\{x_k\}$. Let us employ a cyclic prefix as done in OFDM, *i.e.*,

$$x_{-l} = x_{N-1-l}, \quad l = 0, \dots, \nu.$$

As done in class given the cyclic prefix,

$$\mathbf{y} = \begin{bmatrix} y_{N-1} \\ \vdots \\ y_0 \end{bmatrix} = \underbrace{\begin{bmatrix} p_0 & \dots & \dots & p_\nu & 0 & \dots & 0 & 0 \\ 0 & p_0 & \dots & p_{\nu-1} & p_\nu & 0 & \dots & 0 \\ & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \\ 0 & \dots & \dots & 0 & p_0 & \dots & \dots & p_\nu \\ p_\nu & 0 & \dots & 0 & 0 & p_0 & \dots & p_{\nu-1} \\ & \ddots & \ddots & \ddots & \ddots & \ddots & & \\ p_1 & \dots & p_\nu & 0 & \dots & 0 & 0 & p_0 \end{bmatrix}}_{\mathbf{P}} \underbrace{\begin{bmatrix} x_{N-1} \\ \vdots \\ x_0 \end{bmatrix}}_{\mathbf{x}} + \underbrace{\begin{bmatrix} z_{N-1} \\ \vdots \\ z_0 \end{bmatrix}}_{\mathbf{z}}. \quad (4)$$

In the derivation of OFDM we used the property that

$$\mathbf{P} = \mathbf{F}^* \mathbf{D} \mathbf{F}, \quad (5)$$

where

$$\mathbf{F}_{p,q} = \frac{1}{\sqrt{N}} \exp\left(-j \frac{2\pi}{N} (p-1)(q-1)\right)$$

and \mathbf{D} is the diagonal matrix with

$$\mathbf{D}_{l,l} = d_l = \sum_{n=0}^{\nu} p_n e^{-j \frac{2\pi}{N} n l}.$$

Using this we obtained

$$\mathbf{Y} = \mathbf{F} \mathbf{y} = \mathbf{D} \mathbf{X} + \mathbf{Z},$$

where $\mathbf{X} = \mathbf{F} \mathbf{x}$, $\mathbf{Z} = \mathbf{F} \mathbf{z}$. This yields the parallel channel result

$$\mathbf{Y}_l = d_l \mathbf{X}_l + \mathbf{Z}_l. \quad (6)$$

If the carrier synchronization is not accurate, then (3) gets modified as

$$y(k) = \sum_{n=0}^{\nu} e^{j2\pi f_0 k} p_n x_{k-n} + z_k, \quad k = 0, \dots, N-1 \quad (7)$$

where f_0 is the carrier frequency offset. If we still use the cyclic prefix for transmission, then (4) gets modified as

$$\underbrace{\begin{bmatrix} y(N-1) \\ \vdots \\ y(0) \end{bmatrix}}_{\mathbf{y}} = \underbrace{\begin{bmatrix} p_0 e^{j2\pi f_0(N-1)} & \dots & p_{\nu} e^{j2\pi f_0(N-1)} & 0 & \dots & 0 & 0 \\ \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots \\ 0 & \ddots & \ddots & \ddots & e^{j2\pi f_0 \nu} p_0 & \dots & e^{j2\pi f_0 \nu} p_{\nu} \\ \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots \\ e^{j2\pi f_0 0} p_1 & \dots & e^{j2\pi f_0 0} p_{\nu} & 0 & \dots & 0 & e^{j2\pi f_0 0} p_0 \end{bmatrix}}_{\mathbf{H}} \underbrace{\begin{bmatrix} x_{N-1} \\ \vdots \\ x_0 \end{bmatrix}}_{\mathbf{x}} + \underbrace{\begin{bmatrix} z_{N-1} \\ \vdots \\ z_0 \end{bmatrix}}_{\mathbf{z}}. \quad (8)$$

i.e.,

$$\mathbf{y} = \mathbf{H} \mathbf{x} + \mathbf{z}$$

Note that

$$\mathbf{H} = \mathbf{S} \mathbf{P},$$

where \mathbf{S} is a diagonal matrix with $\mathbf{S}_{l,l} = e^{j2\pi f_0(N-l)}$ and \mathbf{P} is defined as in (4).

[6pts] (a) Show that for $\mathbf{Y} = \mathbf{F} \mathbf{y}$, $\mathbf{X} = \mathbf{F} \mathbf{x}$,

$$\mathbf{Y} = \mathbf{G} \mathbf{X} + \mathbf{Z} \quad (9)$$

and prove that

$$\mathbf{G} = \mathbf{F} \mathbf{S} \mathbf{F}^* \mathbf{D}.$$

[6pts] (b) If $f_0 \neq 0$, we see from part (a) that \mathbf{G} is no longer a diagonal matrix and therefore we do not obtain the parallel channel result of (6). We get inter-carrier interference (ICI), *i.e.*, we have

$$\mathbf{Y}_l = \mathbf{G}_{l,l} \mathbf{X}_l + \underbrace{\sum_{q \neq l} \mathbf{G}(l,q) \mathbf{X}_q}_{\text{ICI + noise}} + \mathbf{Z}_l, \quad l = 0, \dots, N-1,$$

which shows that the other carriers interfere with \mathbf{X}_l . Compute the SINR (signal-to-interference plus noise ratio). Assume $\{\mathbf{X}_l\}$ are i.i.d, with $\mathbb{E}|\mathbf{X}_l|^2 = \mathcal{E}_x$. You can compute the SINR for the particular l and leave the expression in terms of $\{G(l, q)\}$.

[6pts] (c) Find the filter \mathbf{W}_l , such that the MMSE criterion is fulfilled,

$$\min_{\mathbf{W}_l} \mathbb{E}|\mathbf{W}_l^* \mathbf{Y} - \mathbf{X}_l|^2.$$

You can again assume that $\{\mathbf{X}_l\}$ are i.i.d with $\mathbb{E}|\mathbf{X}_l|^2 = \mathcal{E}_x$ and that the receiver knows \mathbf{G} . You can now state the answer in terms of \mathbf{G} .

[7pts] (d) Find an expression for $\mathbf{G}_{l,q}$ in terms of $f_0, N, \{d_l\}$. Given this and (b), what can you conclude about the value of f_0 . For what values of f_0 do you think that the inter-carrier interference problem is important?

Hint: Use the summation of the geometric series hint given in first page.

Problem 3

[MULTIPLE ACCESS CHANNEL AND TRANSMIT CODE (30pts)]

Consider a two user multiple access channel where each user has two transmit antennas and the receiver has two antennas (see Figure).

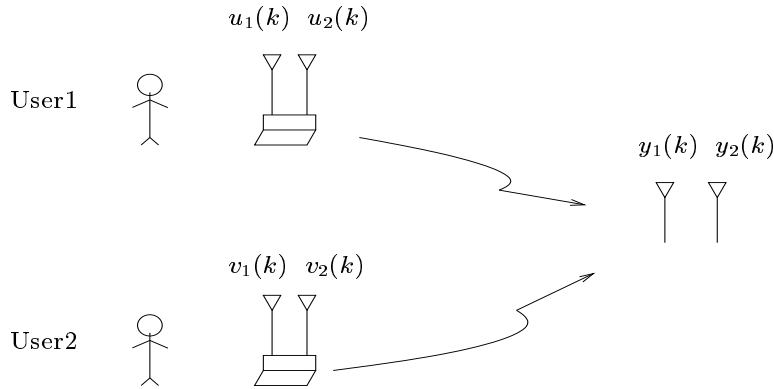


Figure 1: Multiple access channel for problem 4.

Let $\mathbf{u}(k) = \begin{bmatrix} u_1(k) \\ u_2(k) \end{bmatrix}$, $\mathbf{v}(k) = \begin{bmatrix} v_1(k) \\ v_2(k) \end{bmatrix}$ be the transmit signal from each user. The receiver gets a linear combination of the transmit signals,

$$y_1(k) = e_1 u_1(k) + e_2 u_2(k) + f_1 v_1(k) + f_2 v_2(k) + z_1(k),$$

$$y_2(k) = h_1 u_1(k) + h_2 u_2(k) + g_1 v_1(k) + g_2 v_2(k) + z_2(k),$$

where $z_i(k) \sim \mathcal{C}\eta(0, \sigma_z^2)$ and $\{z_i(k)\}$ is i.i.d circularly symmetric Gaussian random variables. Now, suppose the users use an Alamouti code, *i.e.*, for user 1 the transmit signal is

$$\begin{aligned} u_1(k) &= a_1, & u_2(k) &= a_2, \\ u_1(k+1) &= -a_2^*, & u_2(k+1) &= a_1^*, \end{aligned}$$

and for user 2, it is

$$v_1(k) = b_1, \quad v_2(k) = b_2,$$

$$v_1(k+1) = -b_2^*, \quad v_2(k+1) = b_1^*.$$

Therefore we get

$$\begin{bmatrix} y_1(k) & y_1(k+1) \end{bmatrix} = \begin{bmatrix} e_1 & e_2 \end{bmatrix} \begin{bmatrix} a_1 & -a_2^* \\ a_2 & a_1^* \end{bmatrix} + \begin{bmatrix} f_1 & f_2 \end{bmatrix} \begin{bmatrix} b_1 & -b_2^* \\ b_2 & b_1^* \end{bmatrix} + \begin{bmatrix} z_1(k) & z_1(k+1) \end{bmatrix} \quad (10)$$

$$\begin{bmatrix} y_2(k) & y_2(k+1) \end{bmatrix} = \begin{bmatrix} h_1 & h_2 \end{bmatrix} \begin{bmatrix} a_1 & -a_2^* \\ a_2 & a_1^* \end{bmatrix} + \begin{bmatrix} g_1 & g_2 \end{bmatrix} \begin{bmatrix} b_1 & -b_2^* \\ b_2 & b_1^* \end{bmatrix} + \begin{bmatrix} z_2(k) & z_2(k+1) \end{bmatrix} \quad (11)$$

[8pts] (a) Prove that (10) can be equivalently rewritten as

$$\tilde{\mathbf{Y}}_1 = \begin{bmatrix} \tilde{y}_1(k) & \tilde{y}_1(k+1) \end{bmatrix} = \begin{bmatrix} a_1 & a_2 \end{bmatrix} \begin{bmatrix} e_1 & -e_2^* \\ e_2 & e_1^* \end{bmatrix} + \begin{bmatrix} b_1 & b_2 \end{bmatrix} \begin{bmatrix} f_1 & -f_2^* \\ f_2 & f_1^* \end{bmatrix} + \begin{bmatrix} \tilde{z}_1(k) & \tilde{z}_1(k+1) \end{bmatrix}$$

and (11) can be rewritten as

$$\tilde{\mathbf{Y}}_2 = \begin{bmatrix} \tilde{y}_2(k) & \tilde{y}_2(k+1) \end{bmatrix} = \begin{bmatrix} a_1 & a_2 \end{bmatrix} \begin{bmatrix} h_1 & -h_2^* \\ h_2 & h_1^* \end{bmatrix} + \begin{bmatrix} b_1 & b_2 \end{bmatrix} \begin{bmatrix} g_1 & -g_2^* \\ g_2 & g_1^* \end{bmatrix} + \begin{bmatrix} \tilde{z}_2(k) & \tilde{z}_2(k+1) \end{bmatrix},$$

where $\tilde{z}_1(k), \tilde{z}_1(k+1), \tilde{z}_2(k), \tilde{z}_2(k+1)$ are i.i.d circularly symmetric complex Gaussian random variables with distribution $\mathcal{C}\eta(0, \sigma_z^2)$. Explicitly write out how $\begin{bmatrix} \tilde{y}_1(k) & \tilde{y}_1(k+1) \end{bmatrix}$, $\begin{bmatrix} \tilde{y}_2(k) & \tilde{y}_2(k+1) \end{bmatrix}$ are related to $\begin{bmatrix} y_1(k) & y_1(k+1) \end{bmatrix}$, $\begin{bmatrix} y_2(k) & y_2(k+1) \end{bmatrix}$ respectively.

[8pts] (b) Let

$$\mathbf{E} = \begin{bmatrix} e_1 & -e_2^* \\ e_2 & e_1^* \end{bmatrix}, \quad \mathbf{F} = \begin{bmatrix} f_1 & -f_2^* \\ f_2 & f_1^* \end{bmatrix}, \quad \mathbf{G} = \begin{bmatrix} g_1 & -g_2^* \\ g_2 & g_1^* \end{bmatrix}, \quad \mathbf{H} = \begin{bmatrix} h_1 & -h_2^* \\ h_2 & h_1^* \end{bmatrix},$$

$$\mathbf{a} = \begin{bmatrix} a_1 & a_2 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} b_1 & b_2 \end{bmatrix}, \quad \tilde{\mathbf{Z}}_1 = \begin{bmatrix} \tilde{z}_1(k) & \tilde{z}_1(k+1) \end{bmatrix}, \quad \tilde{\mathbf{Z}}_2 = \begin{bmatrix} \tilde{z}_2(k) & \tilde{z}_2(k+1) \end{bmatrix}.$$

Then the equations (10,11) can be written as

$$\begin{bmatrix} \tilde{\mathbf{Y}}_1 & \tilde{\mathbf{Y}}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{a} & \mathbf{b} \end{bmatrix} \begin{bmatrix} \mathbf{E} & \mathbf{H} \\ \mathbf{F} & \mathbf{G} \end{bmatrix} + \begin{bmatrix} \tilde{\mathbf{Z}}_1 & \tilde{\mathbf{Z}}_2 \end{bmatrix}.$$

Prove that

$$\mathbf{W} = \begin{bmatrix} \mathbf{I}_2 & -\mathbf{E}^{-1}\mathbf{H} \\ -\mathbf{G}^{-1}\mathbf{F} & \mathbf{I}_2 \end{bmatrix}$$

decouples the signals from user 1 and 2, *i.e.*,

$$\begin{bmatrix} \check{\mathbf{Y}}_1 & \check{\mathbf{Y}}_2 \end{bmatrix} = \begin{bmatrix} \tilde{\mathbf{Y}}_1 & \tilde{\mathbf{Y}}_2 \end{bmatrix} \mathbf{W} = \begin{bmatrix} \mathbf{a} & \mathbf{b} \end{bmatrix} \begin{bmatrix} \tilde{\mathbf{H}} & \mathbf{0} \\ \mathbf{0} & \tilde{\mathbf{G}} \end{bmatrix} + \begin{bmatrix} \check{\mathbf{Z}}_1 & \check{\mathbf{Z}}_2 \end{bmatrix}, \quad (12)$$

where $\check{\mathbf{Z}}_1, \check{\mathbf{Z}}_2$ are still Gaussian.

[9pts] (c) Prove that $\tilde{\mathbf{H}}$ and $\tilde{\mathbf{G}}$ are of the form

$$\tilde{\mathbf{H}} = \begin{bmatrix} \tilde{h}_1 & -\tilde{h}_2^* \\ \tilde{h}_2 & \tilde{h}_1^* \end{bmatrix}, \quad \tilde{\mathbf{G}} = \begin{bmatrix} \tilde{g}_1 & -\tilde{g}_2^* \\ \tilde{g}_2 & \tilde{g}_1^* \end{bmatrix}.$$

Hint: You do not need to explicitly write out the expressions for $\tilde{h}_1, \tilde{h}_2, \tilde{g}_1, \tilde{g}_2$.

[5pts] (d) In (12) it is seen that

$$\begin{aligned}\check{\mathbf{Y}}_1 &= \mathbf{a}\tilde{\mathbf{H}} + \check{\mathbf{Z}}_1, \\ \check{\mathbf{Y}}_2 &= \mathbf{b}\tilde{\mathbf{G}} + \check{\mathbf{Z}}_2.\end{aligned}$$

Show that

$$\begin{aligned}\check{\mathbf{Y}}_1\tilde{\mathbf{H}}^* &= \|\tilde{\mathbf{h}}\|^2 [a_1 \ a_2] + \check{\mathbf{Z}}_1\tilde{\mathbf{H}}^*, \\ \check{\mathbf{Y}}_2\tilde{\mathbf{G}}^* &= \|\tilde{\mathbf{g}}\|^2 [b_1 \ b_2] + \check{\mathbf{Z}}_2\tilde{\mathbf{G}}^*,\end{aligned}$$

where $\tilde{\mathbf{h}} = [\tilde{h}_1 \ \tilde{h}_2]$, $\tilde{\mathbf{g}} = [\tilde{g}_1 \ \tilde{g}_2]$. This completes the decoupling of the individual streams of the multiple access channel.

[Bonus 5pts] (e) If $h_1, h_2, g_1, g_2, e_1, e_2, f_1, f_2$ are i.i.d and have distribution $\mathcal{C}\eta(0, 1)$, can you guess the diversity order for detecting a_1, a_2, b_1, b_2 ?

Problem 4

[RELAY DIVERSITY (30pts)]

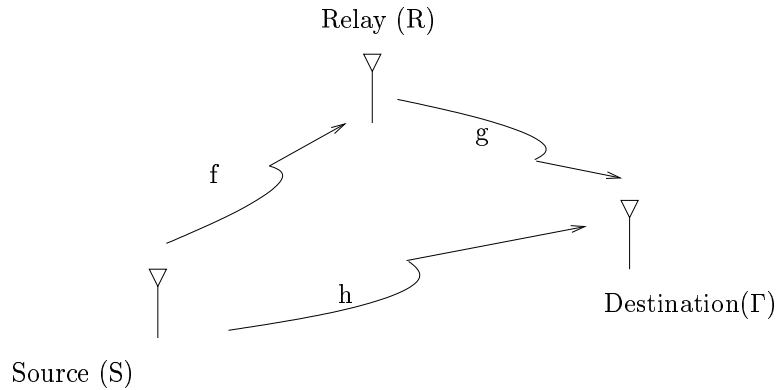


Figure 2: Communication using relay.

In a wireless network let us assume that there are three nodes, where the source (\mathcal{S}) wants to transmit information to the destination (\mathcal{T}) and can obtain help from a relay (\mathcal{R}). Assume that the channels are block time-invariant over a transmission block of size T . We use the following transmission protocol over a block of time of length T . Let $\{s(k)\} \in \{a, -a\}$ be a

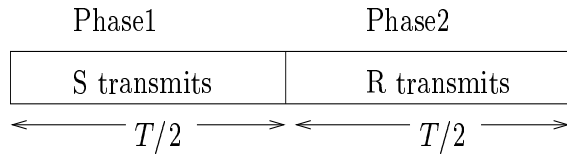


Figure 3: Transmission protocol.

binary information sequence that source \mathcal{S} wants to convey to the destination \mathcal{T} . Then, for the first phase the relay receives $y_{\mathcal{R}}(k)$ and the destination receives $y_{\mathcal{T}}^{(1)}(k)$, with

$$y_{\mathcal{R}}(k) = fs(k) + z_{\mathcal{R}}(k), \quad (13)$$

$$y_{\mathcal{T}}^{(1)}(k) = hs(k) + z_{\mathcal{T}}(k), \quad (14)$$

where $z_{\mathcal{R}}(k), z_{\mathcal{T}}(k) \sim \mathbf{C}\eta(0, \sigma^2)$ are i.i.d, circularly symmetric complex Gaussian noise. We also assume a fading channel, $f, g, h \sim \mathbf{C}\eta(0, 1)$ and are independent of each other. Assume that g, h are known at \mathcal{T} , f is known at \mathcal{R} , but they are unknown at \mathcal{S} (except for part (c)) In the second phase for parts (a), (b),

$$y_{\mathcal{T}}^{(2)}(k) = gu(k) + z_{\mathcal{T}}(k)$$

where $u(k)$ is the signal transmitted by the relay and $g \sim \mathbf{C}\eta(0, 1)$.

- [6pts] (a) Suppose the relay was absent, *i.e.*, $u(k) = 0$, then give an expression (or bound) on the average error probability of $\{s(k)\}$ averaged over the channel realizations h . What is the diversity order, *i.e.*,

$$\lim_{\text{SNR} \rightarrow \infty} \frac{-\log(\bar{P}_e(\text{SNR}))}{\log(\text{SNR})}$$

for the detection of $\{s(k)\}$.

- [12pts] (b) Suppose that the relay \mathcal{R} attempts to decode $\{s(k)\}$ in phase 1 and transmits $u(k) = \hat{s}_{\mathcal{R}}(k)$ in phase 2. That is, it sends the decoded sequence to \mathcal{T} . Assume now that there is an oracle which tells the destination \mathcal{T} if relay \mathcal{R} has decoded correctly or not. Note that the oracle just lets \mathcal{T} know if $\hat{s}_{\mathcal{R}}(k) = s(k)$ but *not* its value. Now, \mathcal{T} can use the received sequence from both phase 1 and phase 2 in order to decode $\{s(k)\}$. Find expressions (or bounds) for the error probability for this decoder averaged over the channel realizations which achieve the *best* diversity order at \mathcal{T} . What is the *best* diversity order that can be achieved at \mathcal{T} for detecting $\{s(k)\}$?

Hint: Develop a receiver strategy that uses the information given by the oracle. You do not need very detailed calculations for obtaining error probability bounds.

- [12pts] (c) Suppose now that we have a new protocol. Phase 1 is as before, where \mathcal{S} transmits and both \mathcal{R} and \mathcal{T} receive the signal as in (13) and (14) respectively. At the end of phase 1, there is a feedback channel from \mathcal{R} to \mathcal{S} which informs \mathcal{S} about the realization of channel f . Now the protocol \mathcal{S} and \mathcal{R} follow is given by: if $|f|^2 \leq c(\text{SNR})$ (where $c(\text{SNR})$ is a function of SNR), then in phase 2, \mathcal{S} repeats the same information it transmitted in phase 1 and the relay \mathcal{R} remains silent, *i.e.*, $\{s(k)\}$ from phase 1 is repeated and $u(k) = 0$ in phase 2. If $|f|^2 > c(\text{SNR})$, then the protocol is as in part (b), *i.e.*, \mathcal{S} remains silent and \mathcal{R} sends the decoded information $u(k) = \hat{s}_{\mathcal{R}}(k)$. Let $c(\text{SNR}) = \frac{1}{\text{SNR}^{1-\epsilon}}$ for an arbitrarily small $\epsilon > 0$,

Assume that an oracle informs the receiver \mathcal{T} whether in phase 2, \mathcal{S} or \mathcal{R} is transmitting. If in phase 2, \mathcal{S} is transmitting, the receiver \mathcal{T} forms the decision variable,

$$\tilde{y}_{\mathcal{T}} = \begin{bmatrix} h^* & h^* \end{bmatrix} \begin{bmatrix} y_{\mathcal{T}}^{(1)} \\ y_{\mathcal{T}}^{(2)} \end{bmatrix}$$

where $y_{\mathcal{T}}^{(1)}, y_{\mathcal{T}}^{(2)}$ are the received signals in phase 1 and phase 2 respectively. On the other hand if in phase 2, the relay \mathcal{R} is transmitting, receiver \mathcal{T} forms the decision variable

$$\tilde{y}_{\mathcal{T}} = \begin{bmatrix} h^* & g^* \end{bmatrix} \begin{bmatrix} y_{\mathcal{T}}^{(1)} \\ y_{\mathcal{T}}^{(2)} \end{bmatrix}$$

where again $y_{\mathcal{T}}^{(1)}, y_{\mathcal{T}}^{(2)}$ are the received signals in phase 1 and phase 2 respectively. The decision rule in both situations is that \mathcal{T} chooses $\hat{s}_{\mathcal{T}} = +a$ if $\Re(\tilde{y}_{\mathcal{T}}) \geq 0$ and $\hat{s}_{\mathcal{T}} = -a$

otherwise. Analyze the performance of this receive strategy *i.e.*, find the diversity order that can be achieved by \mathcal{T} for $\{s(k)\}$. Note that we are looking for diversity order and so we do not necessarily need a detailed analysis to find the diversity order.

Hint: Condition on appropriate error events at the relay and use error probability bounds. You can also use properties given in the hints in the first page.